



## INTELLIGENT LOGISTICS ROBOT SYSTEM







## | Core Advantages |

### **Professional Logistics Planning**

We deeply explore user needs from the perspective of partnership, and deeply customize solutions with logistics experts. We use professional scientific means to verify, realize value through products and the whole process, and meet customer's expectations for logistics.



Digging Needs





Global Simulation







#### Mobile Chassis

Fully diversified chassis forms (wheel type, bridge type, differential speed, omnidirectional, steering wheel) can be quickly and flexibly customized



#### Autonomous Navigation

Industrial complex semiopen environment, millimeter-level full-cycle accuracy, chain data-driven algorithm evolution



#### Smart Hardware

Full-level autonomous hardware (sensing-co munication-drive-control), embedded visual configuration software and algorithms



#### Smart Device

Intelligent support for the full life cycle of intelligent robots (AMR/ AGV)



#### Safety Guarantee

The safety loop formed by sensor control (laser, ultrasonic, infrared sensor, safety bumper) and functional safety (FS) ensures the safety in the working environment



Configuration Software

#### GUOZI ROBOT ADVANCED CONFIGURATION ENVIRONMENT

Create a Smarter Future With Robots



Fully respond to various customization needs



Facilitates the construction of various products and applications

## RAAT Robot As A Tool

Create a Smarter Future With Robots

The core characteristics of RAAT are high adaptability and high flexibility. Compared with robots that must work based on fixed routes, rules, and standardized requirements, we do not need to customize solutions due to the diversity and complexity of scenarios. Our robots will be more adaptable to various complex and mixed collaborative industrial scenarios. It can achieve flexible recognition of objects in the scene, and finally achieve "low cost, maintenance-free", allowing robots to have broader application scenarios.







# RAAS Robot As A Service

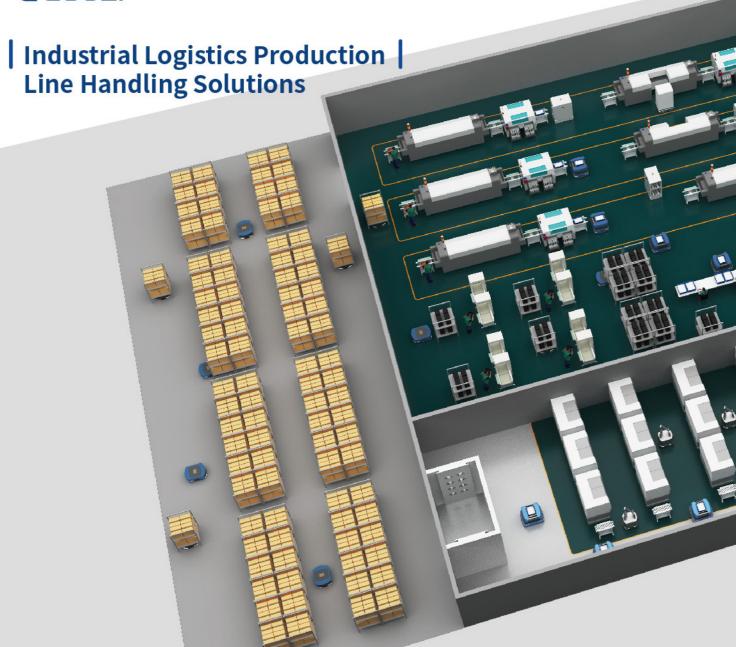
Provide Intelligent Solutions for Applications in Various Industries

We pay attention to the deep cultivation of the industry and the accumulation and replication of scenarios. We understand the needs of the industry, are proficient in process technology, and are committed to solving customer pain points, so as to truly realize the implementation of user needs, intelligent solutions, and synergy of integrated systems.





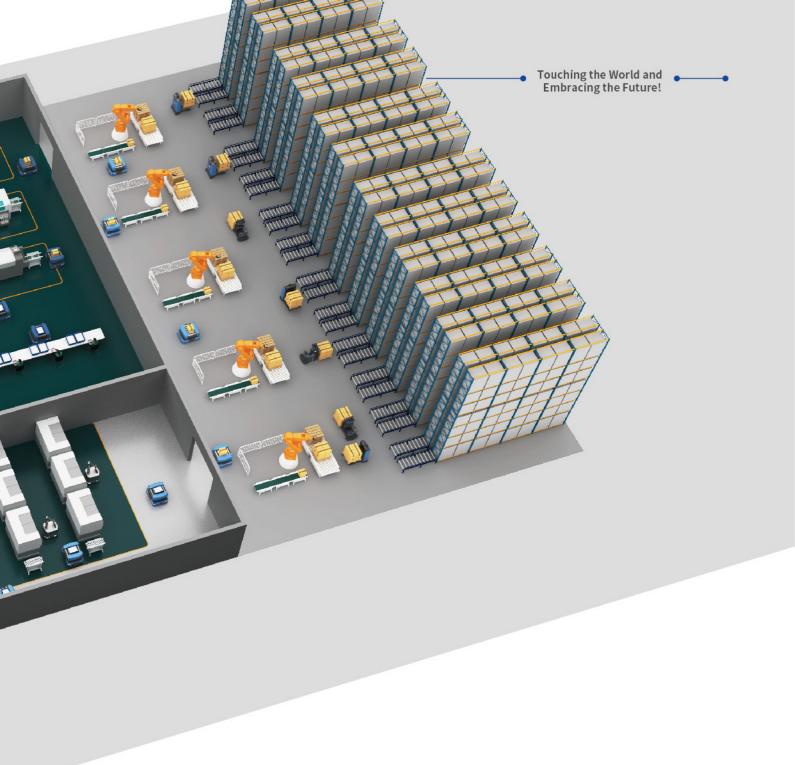




### Project Overview

Guozi robot industrial logistics production line handling solutions based on flexible handling robots, with the robot dispatching management system REX as the core, breaks the logistics handling bottleneck of the discrete process of the factory, redefines intelligent handling, improves production efficiency, and greatly reduces labor costs.

The flexible handling robot inventively adopts the four product design concepts of "dive-in handling, traction handling, shuttle handling, and fork-type handling", covering the entire scene of production line handling, and can efficiently complete the rapid transfer of materials in various production lines/stations, fully automatic loading and unloading as well as the realization of cross-floor and cross-plant transportation, open up the material flow of the entire production line, suitable for automobile manufacturing, construction machinery, 3C electronics, photovoltaics, semiconductors, tobacco and other industries.



## **Project Highlights**

#### Multi-scenario

Various types of car bodies are designed to realize material handling between various stations in different production lines, and fully automatic loading and unloading of materials.

#### Auto-docking

Customize the connection design according to different production line sizes, and flexibly connect roller, conveyor belts, lifting mechanisms, and ASPS

#### Auto-handling

The system provides a Webservice interface, which can connect with the enterprise MES/WMS system, and automatically issue tasks to robots to realize fully autonomous handling.

#### **Multiple Vehicles**

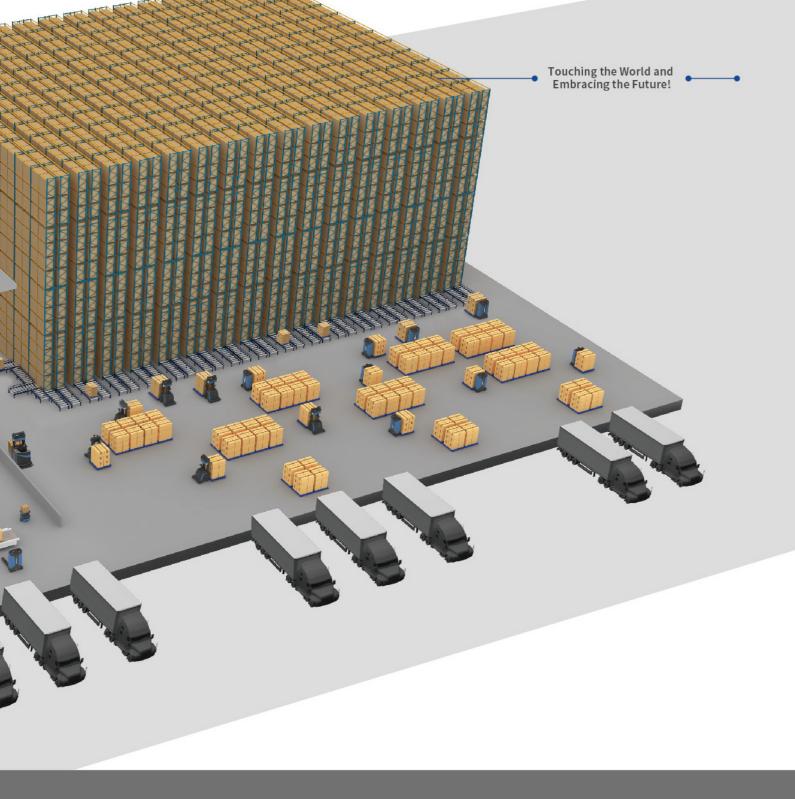
It supports simultaneous dispatching of multiple types of robots, and can flexibly plan and adjust the robot path according to the needs of the production line to ensure the best operating efficiency.

#### User Friendly

The system supports independent map modification, real-time monitoring of robot operation status, real-time position, and intelligent operation and maintenance.



Guozi warehousing logistics picking solutions based on flexible picking robots, with the robot dispatching management system REX as the core, and based on the efficient and accurate picking, it provides solutions that can be applied to a variety of scenarios, including relay picking, station picking, online picking, etc.



## **Project Highlights**



The picking efficiency of robots is more than 30% higher than manual picking. High

High racks rather than the traditional manual work space and can effectively increase the warehouse volume by more than 30-40%. Accurate

> 99.99% picking accuracy ensures accurate storage operations.

Stable

Efficiency balanced outout, improving the overall warehouse operation performance by more than 40%. Lasting

24-hour uninterrupted operation, improving the efficiency of the whole warehouse by more than 50%.

# Intelligent Forklift Robot





	Product I	landling Forklift AGV	Stacking Forklift AGV
	Dimensions (mm)	2254×1177×2193	2459×1177×2330
	Weight(Kg)	1390	1230
Basic Parameters	Rated Load(Kg)	3000	2000
	Lifting Height (mm) can be customized	205	3000
	Fork Size(mm)	1220×180×65	1220×180×65
Navigation	Navigation Method	Laser Slam/Reflector	Laser Slam/Reflector
Performance	Positioning Accuracy (mm)	±5	±5
	Maximum Moving Speed (no load) (m/s)	1.5	1.5
Motion Performance	Maximum Moving Speed (full load) (m/s)	1.2	1.2
	Maximum Gradeability (full load/no load) (	(%) 6/8	5/8
	Safety Sensor	Front, back and sides	Front, back and sides
Safety	Safety Bumper	Available	Available
	Emergency Button	Front and sides	Front and sides
	Battery Type	Iron Phosphate Battery	Iron Phosphate Battery
	Rated Voltage (V)	24V	24V
Battery	Battery Capacity (Ah)	180Ah	180Ah
	Battery Cycles	2500times	2500times
	Rated Operating Time (H)	6~8h	6~8h
	Flexible Entry	Optional	Optional
Other Functional	3D Protection	Optional	Optional
Customization	Natural Stacking	Unavailable	Optional







Counterbalanced Forklift AGV	3T Counterbalanced Forklift AGV	2T Reach Forklift AGV
3050×1200×2273	3746×1290×3005	2812×1290×2426
2325	5750	2500
1500	3000	2000
3000	4500	2700
1220×100×45	1200×150×50	1150×122×45
Laser Slam/Reflector	Laser Slam/Reflector	Laser Slam/Reflector
±5	±5	±5
1.5	1.2	1.5
1.2	1.0	1.2
5/8	5/8	5/8
Front, back and sides	Front, back and sides	Front, back and sides
Available	Available	Available
Front and sides	Front and sides	Front and sides
Iron Phosphate Battery	Iron Phosphate Battery	Iron Phosphate Battery
24V	48V	24V
180Ah	404Ah	252Ah
2500times	2500times	2500times
6~8h	6~8h	6~8h
Optional	Optional	Optional
Optional	Optional	Optional
Optional	Optional	Optional

## Intelligent Handling Robot





	Product	Ants 3	Ants 6
	Dimensions L*W*H(mm)	795×560×285	948×730×265
	Lifting Plate Size L*W*H(mm)	691×521×11.5	Ф644×14
	Rated Load(kg)	400	800
	Weight (kg)	100	200
Basic Parameters	Clearance From the Ground (mm)	20	20
raiailleteis	Rotation Diameter (mm)	855	950
	Lifting Distance(mm)	60	60
	Lifting Time (s)	3	3
	Function of AGV Rotating Without Goods Ro	otating Available	Available
	Navigation Mode (Q/L)	QR Code/Laser Reflector	QR Code/Laser Reflector
Navigation	Stop Accuracy (mm)	±5	±5
Performance	Stop Angle Accuracy(mm)	<0.5	<0.5
	Movement Method	Forward, Reverse, Turn, Rotate	Forward, Reverse, Turn, Rotate
	Rated Moving Speed (no load)(m/s)	2.0	2.0
	Rated Moving Speed (full load)(m/s)	1.5	1.5
Motion Performance	Maximum Grade-ability (full load/no load)	6 3/5	3/5
	Obstacle Climbing Ability(Full Load)(mm)	5	5
	Gap Crossing Ability(Full Load)(mm)	8	8
Network	Network Configuration	5.8GHz WiFi/5G	5.8GHz WiFi/5G
Performance	3D Protection	Optional	Optional
	Obstacle Detection Mode	Front Laser Detection(Back Optional)	Front Laser Detection(Back Optional)
	Max Detection Range(m)	4	4
Safety	Front Laser Max Detection Angle(°)	240	190
	Back Laser Max Detection Angle(°)	160	160
	Collision Detection	ront&Back Safety Bumpers+E-stop Button	Front&Back Safety Bumpers+E-stop Button
	Sound and Light Alarm	Available	Available
	Battery Type	Lithium Iron Phosphate Batteries	Lithium Iron Phosphate Batteries
Pattory	Rated Voltage (V)	51.2	51.2
Battery	Rated Operating Time (H)	8	8
	Charge-discharge Ratio	1:7	1:6







Ants 10	Ants 10 CE&UL	Ants 15
1146×810×275	1141×810×275	1146×810×275
1080×770×10	855×710×10	1080×770×10
1100	1000	1600
210	210	210
30	30	30
1150	1150	1150
68	68	68
4.6	4.6	6
Available	Available	Available
QR Code/Laser Reflector	QR Code/Laser Reflector	QR Code/Laser Reflector
±5	±5	±5
<0.5	<0.5	<0.5
Forward, Reverse, Turn, Rotate	Forward, Reverse, Turn, Rotate	Forward, Reverse, Turn, Rotate
1.6	1.6	1.2
1.5	1.5	1
3/5	3/5	3/5
5	5	5
8	8	8
5.8GHz WiFi/5G	5.8GHz WiFi/5G	5.8GHz WiFi/5G
Optional	Optional	Optional
Front Laser Detection(Back Optional)	Front Laser Detection(Back Optional)	Front Laser Detection(Back Optional)
4	4	4
240	200	240
160	160	160
Front&Back Safety Bumpers+E-stop Button	Front&Back Safety Bumpers+E-stop Button	Front&Back Safety Bumpers+E-stop Button
Available	Available	Available
Lithium Iron Phosphate Batteries	Lithium Iron Phosphate Batteries	Lithium Iron Phosphate Batteries
51.2	51.2	51.2
8	8	8
1:6	1:6	1:6

# Intelligent Picking Robot





	Product	P4 (CE Version Available)	P4-D (Double Deep)	
	Dimensions (mm)	1736×880×5275	1739×880×5275	
Basic	Weight (kg)	550	560	
	Standard AGV Bin Range L*W*H(mm)	L:300~610 W:360~400 H:100~400	L:300~610 W:340~400 H:100~400	
Parameters	Standard Mast Layers	5 layers, 30 kg each, max custom 8 layers	5 layers, 30 kg each, max custom 8 layers	
	Rated Tine Load (kg)	30	30	
	Rated Handling Load (kg)	250	250	
Navigation	Navigation Method	QR Code Navigation (camera)	QR Code Navigation (camera)	
Performance	Secondary Stop Accuracy (single) (mm)	±10	±10	
M-4'	Rated Running Speed (no load) (m/s)	1.2	1.2	
Motion Performance	Rated Running Speed (full load) (m/s)	1	1	
	Grade-ability (full load)	<5% (3°)	<5% (3°)	
	Container Secondary Positioning Method	QR Code Positioning (camera) (contour positioning optional)	QR Code Positioning (camera)+ Contour Positioning (laser)	
	Minimum Docking Height(mm)	310	310	
	Maximum Docking Height(mm)	4945	4945	
Network	Lifting speed (no load/full load) (m/s)	0.5/0.5	0.5/0.5	
Performance	Container Secondary Placement Accuracy (r	mm) ±10	±13	
	Secondary Lifting Stop Accuracy(mm)	±1	±1	
	Fork Tine Telescopic Distance(mm)	0-935	0-1600	
	Fork Tine Telescopic Secondary Stop Accura	cy (mm) ±1	±1	
Safety	Network Configuration	5.8GHz WiFi/5G	5.8GHz WiFi/5G	
Battery	Rated Working Time (h)	8	8	

## Touching the World and Embracing the Future!





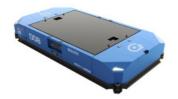
P4-F (Hold)	P4-X (Adaptive Fork)
1720×880×5275	1739×880×5275
540	560
L:300~700 W:300~550 H:100~400	L:300~610 W:200~400 H:100~400
5 layers, 50 kg each, max custom 5 layers	5 layers, 30 kg each, max custom 8 layers
50	30
250	250
QR Code Navigation (camera)	QR Code Navigation (camera)
±10	±10
1.2	1.2
1	1
<3% (2°)	<5% (3°)
Contour Localization (depth camera)	QR Code Positioning (camera)+ Contour Positioning (laser)
430	310
4915 (depends on the height of the bin)	4945
0.5/0.5	0.5/0.5
±13	±13
±1	±1
0-1000	0-935
±1	±1
5.8GHz WiFi/5G	5.8GHz WiFi/5G
8	8

## Intelligent Heavy Duty Robot





	Product	3T Heavy Duty AGV	4T Heavy Duty AGV
	Dimensions L*W*H(mm)	Customized	Customized
	Rated Load(kg)	3000	4000
	Weight (kg)	1070	1900
Basic Parameters	Chassis Clearance (mm)	40	50
raiailleteis =	Rotation Diameter (mm)	2200	6000
	Lifting Height(mm)	330	600
	Drive Wheel Spacing (mm)	1480 (mm)	4200 (mm)
	Navigation Method	QR Code /Laser /Magnetic Navigation	QR Code /Laser / Magnetic Navigation
	Navigation and Positioning Accurac	y (mm) ±10	±10
Navigation Performance	Stop Position Accuracy (mm)	±10	±10
renormance	Secondary Positioning Accuracy (single vehicle/multi-vehicle) (mm)	±10	±10
	Stop Angle Accuracy()	<0.5	<0.6
	Movement Method Fo	orward, Backward, Turn, Rotate, Traverse	Forward, Backward, Turn, Rotate, Traverse
	Drive Mode	Steering wheel	Steering wheel
	Braking Method	Electromagnetic Brake	Electromagnetic Brake
	Braking Distance (mm)	234mm	321mm
Motion Performance	Rated Moving Speed (no load)(m/s)	0.6~0.8/0.4~0.6	0.6~0.8/0.4~0.6
	Rated Moving Speed (full load)(m/s)	0.8/0.6	0.8/0/6
	Max Moving Speed (full load) (m/s)	0.8/0.6	0.8/0/6
	Average Moving Speed (full load) (m/s) (efficiency calculation)	0.6	0.6
Network Performance	Network Configuration	802.11b/g/n/ac	802.11b/g/n/ac
	Obstacle Detection Method	Laser Detection (diagonal)	Laser Detection (diagonal)
Safety	Max Detection Range (m)	4m	4m
	Safety Bumper	all-around safety bumper detection	all-around safety bumper detection





6T Heavy Duty AGV
Customized
6000
2200
40
3400
380
2404 (mm)
QR Code /Laser /Magnetic Navigation
±10
±10
±10
<0.5
Forward, Backward, Turn, Rotate, Traverse
Steering wheel
Electromagnetic Brake
191mm
0.5~0.7/0.3~0.45
0.7/0.45
0.7/0.45
0.4
802.11b/g/n/ac
Laser Detection (diagonal)
4m
all-around safety bumper detection

	Product	Crabs 20
	Dimensions L*W*H(mm)	1868×618×405
	Rated Load(kg)	2000
Basic	Weight (kg)	450
Parameters	Chassis Clearance (mm)	25
	Rotation Diameter (mm)	1967
	Lifting Height(mm)	80
	Navigation Method	QR Code / Laser / Magnetic Navigation
Navigation	Stop Position Accuracy (mm)	±5
Performance	Stop Angle Accuracy(°)	<0.5
	Movement Method	Forward, Backward, Turn, Rotate, Traverse
	Drive Mode	Steering wheel
	Rated Moving Speed (no load)(	m/s) 1.2
Motion Performance	Rated Moving Speed (full load)	(m/s) 0.6
renormance	Rated Traversing Speed (no loa	d) (m/s) 0.6
	Rated Traversing Speed (full loa	ad) (m/s) 0.4
	Grade-ability (full load\no load	) 3/5
Network Performance	Network Configuration	5.8GHz WiFi/5G
	Obstacle Detection Method	Front Laser Detection (Back Laser Optional)
	Front Laser Max Detection Angl	e(°) 270
Safety	Back Laser Max Detection Angle	e() 270
	Contact Detection 4 as	round Safety Bumper + Emergency Stop Button
	Audible&Visual Alarm	Available
Duration	Rated Operating Time (H)	8
Performance	Charge-discharge Ratio	1:5

# SLIM Intelligent Forklift AGV



	Product SLIN	M Stacking Robot (CE Optional)	SLIM Handling Robot	
	Dimensions (mm)	1750×882×2040	1684×955×2035	
	Weight(Kg)	700	580	
Basic Parameters	Rated Load(Kg)	1400	2000	
rarameters	Lifting Height (mm) can be customiz	red 1600	205	
	Fork Size(mm)	1220×180×65	1220×180×65	
Navigation	Navigation Method	Laser Slam/Reflector	Laser Slam/Reflector	
Performance	Positioning Accuracy (mm)	±5	±5	
	Maximum Moving Speed (no load) (n	n/s) 1.5	1.5	
Motion Performance	Maximum Moving Speed (full load) (	m/s) 1.2	1.2	
	Maximum Grade-ability (full load/no	o load) (%) 3/5	3/5	
	Safety Sensor	Front, back and sides	Front, back and sides	
Safety	Safety Bumper	Available	Available	
	Emergency Button	Front and sides	Front and sides	
	Battery Type	Iron Phosphate Battery	Iron Phosphate Battery	
	Rated Voltage (V)	24V	24V	
Battery	Battery Capacity (Ah)	180Ah	180Ah	
	Battery Cycles	2500times	2500times	
	Rated Operating Time (H)	7~10h	7~10h	
	Flexible Entry	Optional	Optional	
Other Functional Customization	3D Protection	Optional	Optional	
Customization	Natural Stacking	Optional	Optional	

#### Touching the World and Embracing the Future!





SLIM Reach Robot (CE Optional)	ATOM-SMART Intelligent Handling Robot
2050×1200×2142	1524×760×597
1890	200
1400	1000
1600	210
1200×150×40	1200×185×65
Laser Slam/Reflector	Laser Slam/Reflector
±5	±10
1.5	ī
1.2	0.8
3/5	1/3
Front, back and sides	Front
Available	Unavailable
Front and sides	sides
Iron Phosphate Battery	Iron Phosphate Battery
24V	48V
180Ah	48Ah
2500times	1500
7~10h	6-8h
Optional	Unavailable
Optional	Optional
Optional	Unavailable

## | Applications |

#### Intelligent Handling Project of High-density Plastic Factory Warehouse

Oil and Gas Chemical Industry Stacking Reach Forklift AGV





#### **Overview**

The client is a large-scale oil refining, chemical, and chemical fiber joint venture under Sinopec. Its high-density warehouse in a plastic factory in Shandong has long used traditional manual forklifts for material transfer. In such condition, the labor intensity is high, and the safety cannot be guaranteed. The low degree of informational makes it even difficult to adapt to the rapid development needs of enterprises.

#### **Solutions**

The intelligent handling solution provided by Guozi Robot is based on multiple stacking reach forklift AGV, adopts various logistics technologies such as natural stacking and conveyor line docking, and is supplemented by a trunk loading system to help client realize a complete intelligent logistics operation process. This system reduces labor costs, improves the efficiency of warehouse transportation and circulation, and has obvious effects of reducing staff and increasing efficiency overall. At the same time, informational and visualization are carried out on site, so that the entire information can be checked, visualized, and controlled, and warehouse logistics can be informative and automated.

#### **Advantages**

- The AGV uses a large-capacity lithium battery and has a self-heating function to ensure the normal use of the AGV when the temperature is low in winter.
- The AGV is precisely positioned and adopts natural stacking technology, without the need for on-site environment modification, to meet the needs of high density storage locations.
- The task balance strategy, dispatching balance strategy, and temporary task transfer scheme are adopted to realize fast operation. To avoid congestion caused by queuing vehicles and ensure operating efficiency. And an automatic loading system is adopted to realize precise positioning of logistics vehicles and complete automatic loading of products.
- Downsize and increasing efficiency: about 50% of manpower is saved, the efficiency of inbound/outbound and storage is increased by 30%, and the direct economic benefits are greatly improved.
- The accuracy of material information in the warehouse area has increased to 99.9%, which greatly reduces the picking errors when shipping.

#### Flexible Logistics Project of Mini Excavator Production Line

Construction Machinery Industry Heavy-Duty Intelligent Handling AGV





#### Overview

The client is one of the world's leading manufacturers in the construction machinery industry, and its miniexcavator manufacturing plant is a benchmark "lighthouse factory" in the construction machinery industry that is less manned, digitized, and intelligent. The factory originally relied on traditional production modes such as manual hoisting and forklift transfer, and the material and parts logistics turnover mode based on manpower has become a bottleneck for the improvement of the company's manufacturing capacity.

#### **Solutions**

Aiming at the client's existing structural parts and production process, Guozi AGV flexible logistics solutions use only 121 AGVs to realize the flexible assembly production line of micro-excavator equipment, as well as the flexible logistics transfer between the structural parts workshop and the final assembly workshop. Through the Guozi REX dispatching system, the AGV completes the transfer task of production materials, pulls the upper and lower body of the excavator to each station for assembly, and the materials on the production line are transported to the designated location on time and on demand through various types of AGV.

#### **Advantages**

After the system is put into operation, the system can automatically schedule materials on the day of production, generate AGV circulation tasks to manage material transportation, distribute goods according to the production rate, and intelligently locate storage, etc., greatly reducing invalid turnover and improving production efficiency. The project helped the customer achieve 81.9% automatic materials discharge, shorten the overall manufacturing cycle by 54.6%, and realize real-time production data collection through applications such as digital twinning, logistics simulation, and online measurement.

- Improve production efficiency: due to the intelligent dispatching of the entire line, the production rate has been improved, and the production efficiency of the workshop has been increased by more than 30%.
- Reduce the backlog of funds: the logistics planning is optimized, the way of material preparation is changed, and the inventory of raw materials, turnover materials, and finished products is reduced.

## **Applications**

#### **Intelligent Picking Project of E-Commerce Warehouse**

E-Commerce Warehousing Industry Multi-Layer Bin Picking Robot





#### Overview

American Staples is currently one of the largest office supplies retailers in the world. In 2016 and 2021, it joined hands with Guozi twice to become a strategic partner. It has deployed more than 2,000 bin-picking robots in total. In their many large warehouses in North America, we have built a stable and reliable intelligent logistics system. This project is Staples in New York, with a warehouse area of more than 12,000 square meters, a total of more than 40,000 storage locations, more than 15,000 active SKUs in the warehouse, and an average daily order volume of more than 20,000 orders.

#### **Solutions**

Guozi e-commerce warehouse intelligent picking solution aims at the three pain points of low warehouse capacity, low efficiency of inbound and outbound, and high document error rate, and uses Picking robots based on high-level shelf storage to greatly increase warehouse storage capacity. Adopting the mode of separate picking and recombination based on popular and unpopular areas, it not only realizes the rapid picking of small-volume "cold materials" with low picking frequency, but also solves the problem that "hot materials" with large-volume picking and high frequency need to be transported by robots multiple times, greatly improving storage efficiency.

### **Advantages**

During the "Black Friday" period, the first annual sales peak in North America after the delivery of the project, a record-breaking task volume of over 70,000 order lines was completed on an average daily inbound and outbound, and the overall picking efficiency was improved by more than 50% compared with traditional manual picking

- The maintenance and update of software and dispatching system can be updated online without stopping, that is, it can be updated while working.
- Dynamic distribution of popular-selling and unpopular-selling products, adjust the location layout at any time, improve picking efficiency, and realize SKU allocation and SKU inventory optimization and efficiency improvement.
- The picking mode combined the mobile robot and the robot arm to further improve the intelligence and picking efficiency of the picking station.
  - Innovative fire avoidance mode to fully guarantee the safety of people, vehicles and goods in the emergency situations

#### **Intelligent Handling Project of Battery Cell Workshop**

Photovoltaic Industry ANTS3 Slim Stacking Robot







#### Overview

The client is one of the top 500 private enterprises in China and a provider of smart energy solutions. Its production base in Jiangsu is responsible for the production of photovoltaic battery cells. The production of photovoltaic cells requires 24 hour uninterrupted operation, which has high requirements for handling accuracy and efficiency. Traditional manual operations are difficult to meet the needs of rapid development of enterprises.

#### **Solutions**

Guozi battery cell intelligent logistics system, applying more than 100 AGVs and integrated equipment such as robotic arms, conveyor lines, and cache WIP, to realize the intelligent flow of empty and full baskets from mixing to slitting and packaging. At the same time, the logistics system is compatible with machine consumable replacement, maintenance, technical upgrades, etc. tasks, and finally achieve the customer handling rate and on-time rate indicators to ensure stable and efficient production.

### **Advantages**

- This project is an intelligent transformation and upgrading of an already operating factory. During the project delivery process, Guozi realized "production while transformation" through the design of the optimal implementation plan to ensure that the production capacity will not be affected.
- The on-site operation channel is narrow, and the robot adopts high-precision laser SLAM and visual positioning technology to achieve safe and stable operation. According to the project process and site conditions, the intelligent material Control System (MCS) and the intelligent dispatching system (RCS) are efficiently integrated to optimize the matching algorithm, achieving optimal efficiency through optimal demand generation, task management, and path planning.
- The whole factory has reduced manpower by 60%, improved cleanliness by 60%, increased automation by 90%, and reduced heavy manual labor by 98%.



## | Applications |

#### **Intelligent Storage and Handling Project of Food Processing Industry**

Food IndustryA NTS-3 Slim Stacking Robot





#### Overview

The client of this project is an Italian manufacturer integrating agricultural planting, production processing, packaging and transportation. The intelligent storage and handling solution provided by Guozi is centered on the lifting handling robot A3 and the Slim stacking robot to realize pallet circulation. The automatic circulation of materials and boxes in the storage area, conveying line, and picking station replaces manual work and helps the intelligent upgrade of the traditional operating mode in food industry.

#### **Solutions**

Guozi intelligent storage and handling solution aims at the characteristics of many types of food and complex production processes in food production warehouses, and inventively uses dynamic storage location management and dynamic route planning in software development to make storage locations and handling more intelligent and effectively in complex environments.

The lifting handling robot A3 transports the fully loaded turnover boxes and food packaging materials to the designated area, and the Slim stacking robot transports the full pallet of packaging materials and the finished food pallets that have completed quality inspection, so as to improve the efficiency of transportation and delivery. The overall product delivery volume is 2-3 times that of the traditional food industry, and the operating efficiency has increased by 80%.

#### **Advantages**

Guozi intelligent storage and handling solution greatly improves the efficiency of warehouse handling and accelerates the operation of food production processes, while ensuring a safe and healthy production and operation process and environment. With more than 100 logistics robots as the core, it brings our client a flexible, intelligent and efficient new model of intelligent warehousing and logistics, and the products & systems used have passed CE certification, helping customers to speed up while fully guaranteeing product quality and safety, and ensuring client, operators and workers are all in a safe and healthy product environment.

#### **Intelligent Storage Project of Pharmaceutical Industry**

#### Pharmaceutical IndustryCounterbalanced Forklift Robot





#### Overview

The client is a state-owned pharmaceutical distribution company with a development history of more than 20 years, and one of the top 100 pharmaceutical distribution companies in China. With the continuous increase in the export volume of medicines, the problems of higher rorrate and low management efficiency in the manual operation mode of the original medicine warehouse have become increasingly critical. There is an urgent need for a highly automated and efficient in telligent logistics solution to improve operation alefficiency.

#### **Solutions**

In August 2018, 5 Guozi laser navigation counterbalanced forklift robots were introduced. The dispatching system REX is integrated with the customer's WMS system to realize 6 types of tasks, including in bound, replenishment, returned goods, sales outbound tasks, purchase and return outbound tasks, and replenishment outbound tasks.

### **Advantages**

- The AGV operation interface is simple and user friendly
- Optimize the docking process between WMS and AGV, reduce the peak operation, and realize the process transformation of warehouse logistics from "person to goods" to "goods to person"
- There are picking and replenishment modes in the operation process. The whole pallet is unloaded at the designated place, and the half pallet is used for the fast entry and exit mode of the bus station to reduce the logistics time.
- Increase the height measurement and weighing module to provide rapid statistics of the number of medicines for pharmaceutical storage
- Reduce the manpower demand by 5-6 people, save about 40% of manpower costs, and realize 24-hour uninterrupted operation.
- Increase the volume of inbound and outbound operations by 100%, increase the efficiency of inbound and outbound warehouses by 30%, and the effect is obvious.

# Touching the World and Embracing the Future!



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